

Art Unit: 2611

—determining a posterior covariance matrix  $\hat{\Sigma}_p$  of the channels using a FFT matrix  $W$ , the previous estimate of the transmitted symbol  $X_p$ , a channel convergence matrix  $\Sigma^{-1}$ , and a Gaussian noise variance  $\sigma^2$  as  $\hat{\Sigma}_p = (W^H X_p^H X_p W / \sigma^2 + \Sigma^{-1})^{-1}$ ;

—where determining a posterior means comprises determining a the posterior mean  $\hat{h}_p$  of a channel impulse response as  $\hat{h}_p = \hat{\Sigma}_p (W^H X_p^H Y / \sigma^2 + \Sigma^{-1} E\{h\})$ , where the received symbol is  $Y$ , and  $E\{h\}$  is a the channel impulse response;

—determining a channel update coefficients matrix  $C$  for recovering the next estimate of the transmitted symbol; and

applying the coefficient matrix  $C$  to the posterior mean  $\hat{h}_p$ , the FFT matrix  $W$ , and the received symbol  $Y$  according to  $\tilde{X}_{p+1} = C^{-1} (\hat{h}_p^H W^H Y)^T$  to optimize the next estimate of the transmitted symbol  $\tilde{X}_{p+1}$ .

Regarding claim 11, in line 4, "symbol transmitted" is replaced by -transmitted *NB 5/11/16* symbol--.

Regarding claim 18, the following version replaces all prior versions in their entirety:

18. The system of claim 12 further comprising:

—means for determining a posterior covariance matrix  $\hat{\Sigma}_p$  of the channels using the FFT matrix  $W$ , the initial estimate of the transmitted symbol  $X_p$ , a channel convergence matrix  $\Sigma^{-1}$ , and a Gaussian noise variance  $\sigma^2$  as  $\hat{\Sigma}_p = (W^H X_p^H X_p W / \sigma^2 + \Sigma^{-1})^{-1}$ ;

—where the means for determining a posterior mean comprises means for determining a the posterior mean  $\hat{h}_p$  of a channel impulse response as  $\hat{h}_p = \hat{\Sigma}_p (W^H X_p^H Y / \sigma^2 + \Sigma^{-1} E\{h\})$ , where the received symbol is  $Y$  and  $E\{h\}$  is a the channel impulse response;